





- [4] Todd Hester, Matej Vecerik, Olivier Pietquin, Marc Lanctot, Tom Schaul, Bilal Piot, Andrew Sendonaris, Gabriel Dulac-Arnold, Ian Osband, John Agapiou, et al. 2017. Learning from demonstrations for real world reinforcement learning. *arXiv preprint arXiv:1704.03732* (2017).
- [5] Maja J Mataric. 1994. Reward functions for accelerated learning. In *Machine Learning: Proceedings of the Eleventh international conference*. 181–189.
- [6] Deepak Pathak, Pulkit Agrawal, Alexei A Efros, and Trevor Darrell. 2017. Curiosity-driven exploration by self-supervised prediction. *arXiv preprint arXiv:1705.05363* (2017).
- [7] Stefan Schaal. 1997. Learning from demonstration. *Advances in neural information processing systems* 9 (1997), 1040–1046.
- [8] Halit Bener Suay, Tim Brys, Matthew E Taylor, and Sonia Chernova. 2016. Learning from demonstration for shaping through inverse reinforcement learning. In *Proceedings of the 2016 International Conference on Autonomous Agents & Multiagent Systems*. International Foundation for Autonomous Agents and Multiagent Systems, 429–437.
- [9] R.S. Sutton and A.G. Barto. 1998. *Reinforcement learning: An introduction*. Vol. 1. Cambridge Univ Press.
- [10] Matthew E Taylor, Halit Bener Suay, and Sonia Chernova. 2011. Integrating reinforcement learning with human demonstrations of varying ability. In *The 10th International Conference on Autonomous Agents and Multiagent Systems-Volume 2*. International Foundation for Autonomous Agents and Multiagent Systems, 617–624.