

for a similar purpose, since S5 is considered an important epistemic logic [22], (see [21] for a recent overview of the research in this direction), and so S5 is a basis of both single and multi-agent logical systems. In that respect, we intend to extend the dynamic proof theory introduced in [5] from sequent-based frameworks to hypersequent-based ones, so that the S5-based hypersequential frameworks presented here will allow an agent to automatically reason about knowledge, beliefs, obligations, and arguments, depending on the interpretation of the modalities.

Another interesting direction for future work is to further increase the expressive power of the frameworks by adding preferences among the arguments. Note that to some extent this may be done already in the current setting. Indeed, when e.g. $\mathcal{S} = \{\Box p, \neg p\}$ is taken as (part of) the set of premises, the argument $\Box p \Rightarrow \Box p$ defeats $\neg p \Rightarrow \neg p$ (this is so since $\Box p \supset p$ is an S5-axiom and double-negation elimination holds in S5), but not vice versa. For a more fine-grained approach one would probably need to incorporate a priority function for expressing preferences among arguments, or introduce a preference criterion, based on the number of modalities in a formula, as is done in other contexts of prioritized or probabilistic argumentation frameworks (see, e.g., [3, 29] for some discussions and further references). In both cases, the attack rules, like those in Example 4.1, would remain the same, but their application will be determined by the relative strengths of the attacking and the attacked arguments (that is, the attacking argument should not be weaker than the attacked argument [3, 15]).

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