A Reinforcement Learning Framework For Studying Group And Individual Fairness

Extended Abstract

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ABSTRACT

Reinforcement learning is a commonly used technique for optimising objectives in decision support systems for complex problem solving. When these systems affect individuals or groups, it is essential to reflect on fairness. As absolute fairness is in practice not achievable, we propose a framework which allows to balance distinct fairness notions along with the primary objective. To this end, we formulate group and individual fairness in sequential fairness notions. First, we present an extended Markov decision process, fMDP, that is explicitly aware of individuals and groups. Next, we formalise fairness notions in terms of this fMDP which allows us to evaluate the primary objective along with the fairness notions that are important to the user, taking a multi-objective reinforcement learning approach. To evaluate our framework, we consider two scenarios that require distinct aspects of the performance-fairness trade-off: job hiring and fraud detection. The objectives in job hiring are to compose strong teams, while providing equal treatment to similar individual applicants and to groups in society. The trade-off in fraud detection is the necessity of detecting fraudulent transactions, while distributing the burden for customers of checking transactions fairly. In this framework, we further explore the influence of distance metrics on individual fairness and highlight the impact of the history size on the fairness calculations and the obtainable fairness through exploration.

KEYWORDS

reinforcement learning; automated decision support; fairness framework; trustworthy AI

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1 INTRODUCTION

Fair and balanced automated decision support is essential, to avoid discrimination or favouritism towards individuals and groups. This is crucial in a wide array of applications, such as finance [9], job hiring [15, 16], epidemic mitigation [3, 4, 8] and fraud detection [12]. Fair decision support systems allow stakeholders to make informed decisions, taking into account an appropriate performancefairness trade-off. This is important, as advice that is proposed by a decision support system might severely impact individuals and groups. Therefore, it is vital to study this matter to enable a wider acceptance of algorithms that support decision makers. As fairness requirements depend on the problem context and the decision maker's concerns, a framework should be capable of dealing with multiple fairness notions, that encompass the ethical considerations of the problem domain and the stakeholders. Consequently, it is important to develop a framework that considers fairness based on sensitive features (e.g., race and gender) and their combinations.

Recent work on fairness in RL has focused on single fairness notions in application-specific solutions [2, 6, 7, 14, 17, 20] and typically relies on reward shaping [2, 10]. However, such approaches do not suffice for real-world decision support problems, as the desired performance-fairness trade-off cannot be described upfront by stakeholders. Furthermore, real-world problems typically require multiple, possibly conflicting, fairness notions [11]. To this end, a multi-objective approach is essential to manage the main objective and to consider multiple fairness framework that is capable of dealing with multiple fairness notions. We experimentally evaluate this framework in job hiring and credit card fraud detection settings.

2 FAIRNESS FRAMEWORK

We define the fairness framework and highlight its requirements and suitability regarding distinct problem settings.

2.1 fMDP and the fairness history

A sequential decision process can be formally described as a Markov Decision Process (MDP) [19], consisting of a set of states S, a set of actions \mathcal{A} , a set of rewards \mathcal{R} and a transition function p: $S \times \mathcal{R} \times S \times \mathcal{A} \rightarrow [0, 1]$ describing the probability of a next state \mathbf{s}_{t+1} and reward r_t given the current state \mathbf{s}_t and action a_t . We extend this standard MDP to an *f* MDP to encode a feedback signal f_t , that concerns an indication whether the chosen action a_t was correct at time *t*.

Existing fairness notions typically concern fair treatment between individuals or groups. We introduce the following notation regarding individuals and groups. I_t refers to the set of individuals involved in the decision process at time *t* and we use $i_t \in I_t$ to refer to an individual of that set. In the job hiring setting, I_t refers to the set of candidates who applied for the job at time t and for which a decision (i.e., hire or reject the applicant) should be made. We refer to the set of all individuals involved in the decision process from the start t = 0 up to time T as I^T . We define $\mathcal{G}_{g,t} \subseteq I_t$ as the individuals of I_t that make up group g. We refer to all individuals involved in the decision process until time *T*, that belong to group *g*, as \mathcal{G}_{a}^{T} . For ease of notation, we assume that groups are predefined and can be empty. In the job hiring setting, \mathcal{G}_q^T refers to the group of men or women, who applied for a job until time T. Given the *f* MDP, we assume that a state s_t provided to the RL agent encodes the individuals I_t and groups G_t involved in the decision at time t. Furthermore, the agent's action a_t encodes the decision impacting the involved individuals I_t and groups G_t , and the feedback I_t and \mathcal{G}_t specifies the correctness of that decision.

Given an *f*MDP, we define a history \mathcal{H}^T until time *T* of past interaction tuples and their feedback regarding the ground truth:

$$\mathcal{H}^T = \{\mathbf{s}_t, a_t, r_t, f_t\}_{t=0}^T \tag{1}$$

We define the encountered states, selected actions and feedback from history \mathcal{H}^T until time T respectively as \mathcal{H}_S^T , \mathcal{H}_A^T and \mathcal{H}_f^T . Consequently, \mathcal{H}_S^T , \mathcal{H}_A^T and \mathcal{H}_f^T are also defined in terms of groups \mathcal{G}^T and individuals \mathcal{I}^T .

2.2 Fairness notions

We formally define a fairness notion \mathscr{F} as a power set \mathscr{P} over \mathscr{G}^T groups (Equation 2) and \mathscr{I}^T individuals (Equation 3), given the history of encountered states \mathscr{H}_S^T , chosen actions \mathscr{H}_A^T and feedback \mathscr{H}_F^T until time T:

$$\mathscr{F}:\mathscr{P}(\mathcal{G}^T)\times\mathscr{P}(\mathcal{H}_S^T)\times\mathscr{P}(\mathcal{H}_A^T)\times\mathscr{P}(\mathcal{H}_f^T)\hookrightarrow\mathbb{R}^-$$
(2)

$$\mathscr{F}:\mathscr{P}(\mathcal{I}^T)\times\mathscr{P}(\mathcal{H}^T_S)\times\mathscr{P}(\mathcal{H}^T_A)\times\mathscr{P}(\mathcal{H}^T_f)\hookrightarrow\mathbb{R}^-$$
(3)

The fairness notion \mathscr{F} is defined as the negative absolute difference in treatment between groups or individuals. The closer \mathscr{F} is to zero, the smaller the difference in treatment is between the groups or individuals. While \mathscr{F} may be intractable due to limitations of defining exact fairness [6], we propose to approximate it with $\hat{\mathscr{F}}$. For a future fairness objective, \mathscr{F} , and by extension its approximation $\hat{\mathscr{F}}$ provide a foundation for a reward signal that can be used with a multi-objective RL approach.

3 RESULTS

As both the job hiring and fraud detection scenario deal with a reward and multiple fairness objectives, the number of policies with suitable trade-offs can scale exponentially. To this end, we use Pareto Conditioned Networks (PCN) [13], as PCN trains a single neural network to approximate all non-dominated policies, by applying supervised learning techniques to improve the policy. We report the learned non-dominated coverage sets for all fairness notions and the main reward [5], across 10 seeds after 500 000 steps. Meaning, the reward vector consists of: the main reward (R) and the fairness notions statistical parity (SP), equal opportunity (EO), overall accuracy equality (OAE), predictive parity (PP), individual fairness (IF) and consistency score complement (CSC) [11, 21].

For the job hiring scenario, we train an agent to hire and maintain a well-performing team of 100 employees from the Belgian population [18], where episodes last for a maximum of 1000 timesteps. We ask the agent to optimise four objectives: {R, SP, EO, IF}. We implement the fairness history as a sliding window of 100 timesteps and use the Bray-Curtis distance metric for the individual fairness notions. Figure 1a shows a representative set of policies from the non-dominated coverage sets. Note how the some of the best learned policies are close to 0 for all group fairness notions, indicating the agent has learned policies which can satisfy more fairness notions than initially requested. In contrast, due to the impact of how the individual fairness notions are defined, it is possible for the agent to find larger differences in non-dominated values among them. However, obtaining a higher CSC or IF comes at the cost of the main reward and some additional group fairness notions.

For the fraud detection scenario, we assume the default parameters of the MultiMAuS simulator [22], but increase the frequency of fraudulent transactions to approximately 10%. We let the agent check transactions for a week, resulting in at most 1000 transactions per episode. We ask the agent to optimise on four objectives: {R, OAE, PP, CSC}. Figure 1b shows the learned trade-offs for two different history sizes. The policies learned by the agent across both window sizes follow similar trade-offs with regards to the reward and the fairness notions. Note that individual fairness is low for both IF and CSC. The largest contributor to this effect is the different base rates for fraudulent transactions between individuals, indicating the agent has mostly focused on improving the requested group fairness notions, at the cost of individual fairness.



Figure 1: Representative policies from the non-dominated coverage sets, with requested objectives in **bold**.

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